

# Automated Inference of Shape Specifications

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- 1 Overview
- 2 `get_data` Example
- 3 `s112d11` Example
- 4 `t11` Example
- 5 Implementation and Experiments

Shape analysis: discover invariants that describe the data structures in a program

Given pre-shapes, infer post-shapes

- TVLA: T. Reps et. al. [POPL'99].
- Xisa: Rival et. al. [POPL'08].

More Automatic

- Bi-abduction: Calcagno et.al. [POPL'09, J.ACM'11], Predator [CAV'11].
  - infer both pre- and post-shapes
  - bottom-up, verify Linux kernel 2.6.25.4 with **2.473MLOC** in **1739.28** seconds ✓
- Forestor: Vojnar et.al. [CAV'13]. top-down
- Cycle proof: James et.al. [SAS'14].

## Frame Inference

$$\Delta_{\text{ante}} \vDash \Delta_{\text{conseq}} * \underline{? \Delta_{\text{frame}}}$$

## Example

```
struct nnode { struct nnode* next }.
```

$$x \mapsto \text{nnode}(n_1) * y \mapsto \text{nnode}(n_1) \vDash y \mapsto \text{nnode}(n_2) * ? \Delta_{\text{frame}}$$

$$\Delta_{\text{frame}} = x \mapsto \text{nnode}(n_1) \wedge x \neq y \wedge y \neq \text{NULL} \wedge n_1 = n_2$$

## Abduction

$$\underline{?\Delta_{\text{pre}} * \Delta_{\text{ante}}} \vDash \Delta_{\text{conseq}}$$

## Example:

$$?\Delta_{\text{pre}} \wedge \text{true} \vDash y \mapsto \text{nnode}(n_2)$$

$$\Delta_{\text{pre}} = y \mapsto \text{nnode}(n_2)$$

Do not infer trivial precondition, i.e. `false`

Abduction + Frame Inference = Bi-Abduction

$$\underline{?\Delta_{\text{pre}} * \Delta_{\text{ante}}} \vDash \Delta_{\text{conseq}} * \underline{?\Delta_{\text{frame}}}$$

Example:

$$?\Delta_{\text{pre}} * x \mapsto \text{nnode}(n_1) \wedge x \neq y \vDash y \mapsto \text{nnode}(n_2) * ?\Delta_{\text{frame}}$$

$$\Delta_{\text{pre}} = y \mapsto \text{nnode}(n_2) \quad \Delta_{\text{frame}} = x \mapsto \text{nnode}(n_1) \wedge x \neq y \wedge y \neq \text{NULL}$$

## Bi-Abduction (Calcagno et. al. [J.ACM'11])

```
1 void free_list(struct snode *x){
2   struct snode *t;
3   while(x!=0){
4     t=x;
5     x=x->next;
6     free(t);
7   }
8 }
```

UNSOUND!

### Aims:

- 1 scalability ✓
- 2 expressive data structures {lists,.. ? }
- 3 soundness ?

# Second-Order Bi-Abduction

- Unknown Predicates as **Second-Order** Variables
- $\mathcal{R} \wedge \Delta_{\text{ante}} \vdash \Delta_{\text{conseq}} * \underline{\Delta_{\text{frame}}}$

$\mathcal{R}$  is a set of relational assumptions

$$\mathcal{R} = \bigwedge_{i=1}^n (\Delta_i @ \Delta_g \Rightarrow \Phi_i)$$

Entailment syntax:  $\Delta_{\text{ante}} \vdash \Delta_{\text{conseq}} \rightsquigarrow (\mathcal{R}, \underline{\Delta_{\text{frame}}})$



# Second-Order Bi-Abduction

Examples:

## Abductive Unfold

$$H(y) * x \mapsto nnode(n_1) \vdash y \mapsto nnode(n_2) \rightsquigarrow (\mathcal{R}, \underline{\Delta_{\text{frame}}})$$

$$\mathcal{R} \equiv H(y) \Rightarrow y \mapsto nnode(n_2) * U(n_2)$$

$$\Delta_{\text{frame}} = x \mapsto nnode(n_1) * \underline{U(n_2)}$$

## Abductive Fold

$$\begin{aligned} x \mapsto nnode(\text{NULL}) * y \mapsto nnode(\text{NULL}) \vdash G(x) \\ \rightsquigarrow (x \mapsto nnode(\text{NULL}) \Rightarrow G(x), y \mapsto nnode(\text{NULL})) \end{aligned}$$

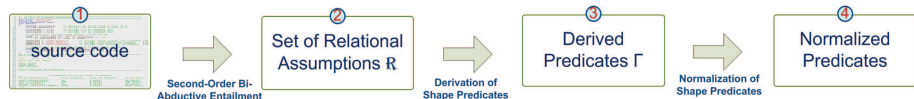
# from Verification to Inference

Research Problem: Given a program, find pre-shape and post-shape such that the program is absence of memory-errors (**null dereference**)?

Solution:

- 1 Assume pre-shape is  $P(..)$ , post-shape is  $Q(..)$
- 2 Transform **requirement** to relational assumptions on  $P, Q$ .  
Denote proof obligations to be met
- 3 Solve

Our framework:



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# Shape Inference: get\_next Example

## Method Specification:

```
requires ptr ↦ node⟨d, p⟩  
ensures ptr ↦ node⟨d, p⟩ ∧ res = p;
```

## Verification

```
1 struct node * get_next(struct node * ptr) {  
  //  $\alpha_1 : ptr \mapsto \text{node}\langle d, p \rangle$   
  // (binding)  $E_1 : \alpha_1 \vdash \exists d_1, p_1 \cdot ptr \mapsto \text{node}\langle d_1, p_1 \rangle$   
2   return ptr->next;  
  //  $\alpha_2 : \exists d_1, p_1 \cdot ptr \mapsto \text{node}\langle d_1, p_1 \rangle \wedge d_1 = d \wedge p_1 = p \wedge res = p_1$   
  // (post)  $E_2 : \alpha_2 \vdash ptr \mapsto \text{node}\langle d, p \rangle \wedge res = p$   
3 }
```

# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(\text{ptr})$       `ensures`  $G(\text{ptr}, \text{res})$ ;

Verification **to Inference**

```
1 struct node * get_next(struct node * ptr) {  
  //  $\alpha'_1 : H(\text{ptr})$   
  //  $(\text{binding})E'_1 : \alpha'_1 \vdash \dots$   
2   return ptr->next;  
  //  $\alpha'_2 : \dots$   
  //  $(\text{post})E'_2 : \alpha'_2 \vdash G(\text{ptr}, \text{res})$ 
```

# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(\text{ptr})$       `ensures`  $G(\text{ptr}, \text{res})$ ;

Verification **to Inference**

```
1 struct node * get_next(struct node * ptr) {  
  //  $\alpha'_1 : H(\text{ptr})$   
  // (binding)  $E'_1 : \alpha'_1 \vdash \exists d_1, p_1 \cdot \text{ptr} \mapsto \text{node}(d_1, p_1)$   
2   return ptr->next;  
  //  $\alpha'_2 : \dots$   
  // (post)  $E'_2 : \alpha'_2 \vdash G(\text{ptr}, \text{res})$   
3 }
```

# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(ptr)$       `ensures`  $G(ptr, res)$ ;

Verification **to Inference**

```
1  struct node * get_next(struct node * ptr) {  
   //  $\alpha'_1 : H(ptr)$   
   // (binding)  $E'_1 : \alpha'_1 \vdash \exists d_1, p_1 \cdot ptr \mapsto node\langle d_1, p_1 \rangle$   
2   return ptr->next;  
   //  $\alpha'_2 : \dots$   
   // (post)  $E'_2 : \alpha'_2 \vdash G(ptr, res)$   
3 }
```

$$E_1' \rightsquigarrow (\mathcal{R}_1, \Delta_{frame}^1)$$

$$\mathcal{R}_1 \equiv H(ptr) \Rightarrow ptr \mapsto node(-, p_1) * U(p_1) \quad \Delta_{frame}^1 = ptr \mapsto node(p_1) * U(p_1)$$

# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(ptr)$       `ensures`  $G(ptr, res)$ ;

Verification **to Inference**  $\mathcal{R}_1 \equiv H(ptr) \Rightarrow ptr \mapsto node(-, p_1) * U(p_1)$

```
1  struct node * (struct node * ptr) {  
    //  $\alpha'_1 : H(ptr)$   
    // (binding)  $E'_1 : \alpha'_1 \vdash \exists d_1, p_1 \cdot ptr \mapsto node(d_1, p_1)$   
2    return ptr->next;  
    //  $\alpha'_2 : \exists d_1, p_1 \cdot ptr \mapsto node(d_1, p_1) * U(p_1) \wedge res = p_1$   
    // (post)  $E'_2 : \alpha'_2 \vdash G(ptr, res)$   
3 }
```



# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(\text{ptr})$       `ensures`  $G(\text{ptr}, \text{res})$ ;

Verification **to Inference**

```
1 struct node * (struct node * ptr) {  
  //  $\alpha'_1 : H(\text{ptr})$   
  // (binding)  $E'_1 : \alpha'_1 \vdash \exists d_1, p_1 \cdot \text{ptr} \mapsto \text{node}(d_1, p_1)$   
2   return ptr->next;  
  //  $\alpha'_2 : \exists d_1, p_1 \cdot \text{ptr} \mapsto \text{node}(d_1, p_1) * U(p_1) \wedge \text{res} = p_1$   
  // (post)  $E'_2 : \alpha'_2 \vdash G(\text{ptr}, \text{res})$   
3 }
```

$$E_2' \rightsquigarrow (\mathcal{R}_2, \Delta_{\text{frame}}^2)$$

$$\mathcal{R}_2 \equiv \text{ptr} \mapsto \text{node}(-, p_1) * U(p_1) \wedge \text{res} = p_1 \Rightarrow G(\text{ptr}, \text{res}) \quad \Delta_{\text{frame}}^2 = U(p_1)$$

# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(ptr)$       `ensures`  $G(ptr, res)$ ;

Relational Assumptions derived:

$$\mathcal{R}_1 \equiv H(ptr) \Rightarrow ptr \mapsto node(-, p_1) * U(p_1)$$

$$\mathcal{R}_2 \equiv ptr \mapsto node(-, p_1) * U(p_1) \wedge res = p_1 \Rightarrow G(ptr, res)$$

Dangling Predicates, such as  $U(p_1)$  :

- Uninstantiated predicates
- Can link pre/post specification

# Shape Inference: get\_next Example

Method Specification:

`requires`  $H(ptr)$     `ensures`  $G(ptr, res)$ ;

Weakest Pre-Predicate:

$$H(ptr) \equiv ptr \mapsto node(., DP)$$

Strongest Post-Predicate:

$$G(ptr, res) \equiv ptr \mapsto node(., DP) \wedge res = DP$$

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# Shape Inference: sll2dll Example

```
1 struct node{struct node* prev;struct node* next;}
2 void node* sll2dll (struct node *x, struct node *q)
  {
3   if(x==NULL) return;
4   else{
5     x->prev=q;
6     sll2dll(x->next,x);
7   }
8 }
```



requires sll(x)      ensures dll(x,q)

# Shape Inference: sll2dll Example

```
1 struct node{struct node* prev;struct node* next;}
2 void node* sll2dll (struct node *x, struct node *q)
  {
3   if(x==NULL) return;
4   else{
5     x->prev=q;
6     sll2dll(x->next,x);
7   }
8 }
```



## Unknown Predicates as Second-Order Variables:

requires  $H(x, q\#)$       ensures  $G(x, q)$

- 1 Infer Relational Assumptions via Second-Order Bi-abduction
- 2 Derive Predicate Definitions
- 3 Normalize Predicate Definitions

# Shape Inference: sll2dll Example. Step 1

```
void sll2dll(struct node* x, struct node* q) {  
  ( $\alpha_1$ ) H(x, q#)  
  if (x==NULL)  
    ( $\alpha_2$ ) H(x, q#)  $\wedge$  x=NULL  
  return;  
  x->prev=q;  
  sll2dll(x->next, x);  
}
```

Post Proving at  $\alpha_2$

$$H(x, q\#) \wedge x=NULL \vdash G(x, q)$$
$$\rightsquigarrow ((A1) : H(x, q\#) \wedge x=NULL \Rightarrow G(x, q), \text{emp} \wedge x=NULL)$$

# Shape Inference: sll2dll Example. Step 1

```
void sll2dll(struct node* x, struct node* q) {  
  ( $\alpha_1$ ) H(x, q#)  
  if (x==NULL)  
    return;  
  ( $\alpha_3$ ) H(x, q#)  $\wedge$  x  $\neq$  NULL  
  x->prev=q;  
  sll2dll(x->next,x);  
}
```

Field Access after  $\alpha_3$ :

$$\alpha_3 \vdash x \mapsto \mathit{node}(x_p, x_n) \rightsquigarrow (\text{A2}, H_p(x_p, q\#) * H_n(x_n, q\#) \wedge x \neq \text{NULL})$$

$$(\text{A2}). H(x, q\#) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \mathit{node}(x_p, x_n) * H_p(x_p, q\#) * H_n(x_n, q\#)$$



# Shape Inference: sll2dll Example. Step 1

```
void sll2dll(struct node* x, struct node* q) {  
  ( $\alpha_1$ ) H(x, q#)  
  if (x==NULL)  
    return;  
  ( $\alpha_3$ ) H(x, q#)  $\wedge$  x  $\neq$  NULL  
  ( $\alpha'_3$ )  $x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q#) * H_n(x_n, q#) \wedge x \neq \text{NULL}$   
  x->prev=q;  
  sll2dll(x->next,x);  
}
```

Field Access:

$$\alpha_3 \vdash x \mapsto \text{node}(x_p, x_n) \rightsquigarrow (\text{A2}, H_p(x_p, q#) * H_n(x_n, q#) \wedge x \neq \text{NULL})$$

$$(\text{A2}). H(x, q#) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q#) * H_n(x_n, q#)$$

# Shape Inference: sll2dll Example

```
void sll2dll(struct node* x, struct node* q) {  
  ( $\alpha_1$ ) H(x, q#)  
  if (x==NULL)  
    return;  
  ( $\alpha'_3$ )  $x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q\#) * H_n(x_n, q\#) \wedge x \neq \text{NULL}$   
  x->prev=q;  
  ( $\alpha_4$ )  $x \mapsto \text{node}(q, x_n) * H_p(x_p, q\#) * H_n(x_n, q\#) \wedge x \neq \text{NULL}$   
  sll2dll(x->next, x);  
}
```

Pre- Proving for recursive call:

$$(\alpha_4) \vdash H(x_n, x\#) \rightsquigarrow (\text{A3}, x \mapsto \text{node}(q, x_n) * H_p(x_p, q\#) \wedge x \neq \text{NULL})$$

$$(\text{A3}). H_n(x_n, q\#) \text{ @ } x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x\#)$$

# Shape Inference: sll2dll Example. Step 1

Relational Assumptions:

$$(A1). H(x, q) \wedge x = \text{NULL} \Rightarrow G(x, q)$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$$

$$(A3). H_n(x_n, q) \ @ \ x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x)$$

$$(A4). x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$$

After this step, we can confirm that the `sll2dll` is **memory-safety**

- **requires**  $H(x, q)$     **ensures**  $G(x, q)$ , and  $\{A1 \wedge A2 \wedge A3 \wedge A4\}$
- However, we wish to go beyond the **memory-safety**

We aim to infer a **understandable** and **reusable** specs, like

$$\text{requires } \text{sll}(x) \quad \text{ensures } \text{dll}(x, q)$$

Key idea: Split relational assumptions of pre- and post-predicates.

- Pre-predicates: strengthened
- Post-predicates: weakened

Steps

- 1 Base Split (with Guard)
- 2 Sort
- 3 Pre-Predicates Synthesis Rules
- 4 Post-Predicates Synthesis Rules

## Step 2.1: Base Split:

$$(A1). H(x, q) \wedge x = \text{NULL} \Rightarrow G(x, q)$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$$

$$(A3). H_n(x_n, q) \text{ @ } x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x)$$

$$(A4). x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$$

$\Rightarrow$

$$(A1a). H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$$

$$(A1b). \text{emp} \wedge x = \text{NULL} \Rightarrow G(x, q)$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$$

$$(A3). H_n(x_n, q) \text{ @ } x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x)$$

$$(A4). x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$$

# Shape Inference: sll2dll Example. Step 2

## Step 2.2: Sort

(A1a).  $H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$

(A1b).  $\text{emp} \wedge x = \text{NULL} \Rightarrow G(x, q)$

(A2).  $H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$

(A3).  $H_n(x_n, q) \ @ \ x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x)$

(A4).  $x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$



## Pre-Preds Assumptions

(A3).  $H_n(x_n, q) \ @ \ x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x)$

(A1a).  $H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$

(A2).  $H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$

## Post-Preds Assumptions

(A1b).  $\text{emp} \wedge x = \text{NULL} \Rightarrow G(x, q)$

(A4).  $x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$

# Shape Inference: sll2dll Example. Step 2

## Step 2.3: Pre-Predicates Synthesis

### Pre-Preds Assumptions

$$(A3). H_n(x_n, q) @ x \mapsto \text{node}(q, x_n) \Rightarrow H(x_n, x)$$

$$(A1a). H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$$



Synthesize  $H_n$  from A3

$$H_n(x_n, q) \equiv H(x_n, x) @ x \mapsto \text{node}(q, x_n)$$

### Pre-Preds Assumptions

$$(A1a). H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$$

# Shape Inference: sll2dll Example. Step 2

## Step 2.3: Pre-Predicates Synthesis

Inline  $H_n$  into  $A2$

Synthesized Predicate Definition:

$$H_n(x_n, q) \equiv H(x_n, x) @ x \mapsto \text{node}(q, x_n)$$

Pre-Preds Assumptions

$$(A1a). H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H_n(x_n, q)$$



Pre-Preds Assumptions

$$(A1a). H(x, q) \wedge x = \text{NULL} \Rightarrow \text{emp} \wedge \text{true}$$

$$(A2). H(x, q) \wedge x \neq \text{NULL} \Rightarrow x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H(x_n, q)$$



# Shape Inference: sll2dll Example. Step 2

## Step 2.3: Pre-Predicates Synthesis

Synthesize  $H$ .

Synthesized Predicate Definition:

$$H_n(x_n, q) \equiv H(x_n, x) @ x \mapsto \text{node}(q, x_n)$$

Pre-Preds Assumptions

$$H(x, q) \Rightarrow (\text{emp} \wedge x = \text{NULL}) \vee \\ (x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H(x_n, q) \wedge x \neq \text{NULL})$$



Synthesized Predicate Definition:

$$H_n(x_n, q) \equiv H(x_n, x) @ x \mapsto \text{node}(q, x_n) \\ H(x, q) \equiv (\text{emp} \wedge x = \text{NULL}) \vee \\ (x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H(x_n, q) \wedge x \neq \text{NULL})$$

# Shape Inference: sll2dll Example. Step 2

## Step 2.4: Post-Predicates Synthesis

Synthesize  $G$ . soundly weaken conjunction into disjunction

Post-Preds Assumptions

$$(A1b). \text{ emp} \wedge x = \text{NULL} \Rightarrow G(x, q)$$

$$(A4). x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$$



$$\text{emp} \wedge x = \text{NULL} \vee x \mapsto \text{node}(q, x_n) * G(x_n, x) \Rightarrow G(x, q)$$



$$H_n(x_n, q) \equiv H(x_n, x) \ @ \ x \mapsto \text{node}(q, x_n)$$

$$H(x, q) \equiv (\text{emp} \wedge x = \text{NULL}) \vee \\ (x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H(x_n, q) \wedge x \neq \text{NULL})$$

$$G(x, q) \equiv (\text{emp} \wedge x = \text{NULL}) \vee (x \mapsto \text{node}(q, x_n) * G(x_n, x))$$

Synthesized Predicate Definition:

$$H_n(x_n, q) \equiv H(x_n, x) @ x \mapsto \text{node}(q, x_n)$$

$$H(x, q) \equiv (\text{emp} \wedge x = \text{NULL}) \vee \\ (x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H(x_n, q) \wedge x \neq \text{NULL})$$

$$G(x, q) \equiv (\text{emp} \wedge x = \text{NULL}) \vee (x \mapsto \text{node}(q, x_n) * G(x_n, x))$$

Other issues:

- 1 Base Split with Guard
- 2 Inline with Guarded Assumptions
- 3 Soundness

# Shape Normalization. Step 3

$$\begin{aligned}H_n(x_n, q) &\equiv H(x_n, x) @ x \mapsto \text{node}(q, x_n) \\H(x, q) &\equiv (\text{emp} \wedge x = \text{NULL}) \vee \\&\quad (x \mapsto \text{node}(x_p, x_n) * H_p(x_p, q) * H(x_n, q) \wedge x \neq \text{NULL}) \\G(x, q) &\equiv (\text{emp} \wedge x = \text{NULL}) \vee (x \mapsto \text{node}(q, x_n) * G(x_n, x))\end{aligned}$$

- 1 Detect Dangling Predicates, e.g.  $H_p(x_p, q)$
- 2 Eliminate Useless Parameters, e.g. parameter  $q$  of  $H(x, q)$
- 3 Resue Predicates, e.g. relate  $H$  with  $sll$  and  $G$  with  $dll$

requires  $sll(x)$       ensures  $dll(x)$

Other Issues:

- 1 Split Predicates
- 2 Lemma Synthesis Mechanism

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- 1 Forward verification
  - $R$  collects the constraints over “unknown shape predicates” required for memory safety
- 2 Sound entailment via second-order bi-abduction
  - $R$  generates the constraints over “unknown shape predicates” required for the entailment to hold
- 3 Derivation of predicate definitions from the constraints
- 4 Normalization for “concise” and “reusable” predicate definitions



```

1 // Iosif et. al. [CADE'13]
2 struct tree{ struct tree* parent; struct tree* left;
3   struct tree* right; struct tree* next;
4 };
5 struct tree* set_right (struct tree* x, struct tree* parent, struct tree* t){
6   x->parent=parent;
7   if (x->right==NULL){
8     x->next = t;
9     return x;
10  } else{
11    struct node* r_most = set_right(x->right, x, t);
12    return set_right(x->left, x, r_most);
13  }
14 }

```



- We introduce two unknown predicates  $H(x)$  and  $G(x, p, res, t)$

struct tree\* tll(struct tree\* x, struct tree\* p, struct tree\* t)  
 requires  $H(x)$  ensures  $G(x, p, res, t)$

- Our analysis generates:

$$H(x) \equiv x \mapsto tree(\_, \_, r, \_) \wedge r = \text{NULL} \\ \vee x \mapsto tree(\_, l, r, \_) * H(l) * H(r) \wedge r \neq \text{NULL}$$

$$G(x, p, res, t) \equiv x \mapsto tree(p, \_, r, t) \wedge res = x \wedge r = \text{NULL} \\ \vee x \mapsto tree(p, l, r, \_) * G(l, x, res, lm) * G(r, x, lm, t) \wedge r \neq \text{NULL}$$



# Second-Order Bi-Abduction

For the tll example the set of constraints  $\mathcal{R}$  is :

```
struct tree* tll
  (struct tree* x,
   struct tree* p,
   struct tree* t) {
  x->parent = p; (1)
  if (x->r = null) {
    x->next = t;
    return x; (2)
  } else {
    struct tree* lm;
    lm = tll(x->r, x, t); (3)
    return tll(x->l, x, lm); (4)
  } (5)
}
```

(1).  $H(x, q, t) \Rightarrow x \mapsto \text{tree}(p, l, r, n) * H_l(l, q, t) * H_r(r, q, t) * H_n(n, q, t) * H_p(p, q, t)$

(2).  $x \mapsto \text{tree}(p, l, r, t) * H_l(l, q, t) * H_p(p, q, t) * H_r(r, q, t) \wedge r = \text{NULL} \wedge \text{res} = x \Rightarrow G(x, p, \text{res}, t)$

(3).  $H_r(r, q, t) \wedge r \neq \text{NULL} \Rightarrow H(r, x, t)$

(4).  $H_l(l, q, t) \Rightarrow H(l, q, lm)$

(5).  $x \mapsto \text{tree}(p, l, r, n) * H_n(n, q, t) * G(r, x, lm, t) * G(l, x, \text{res}, lm) \wedge r \neq \text{NULL} \Rightarrow G(x, p, \text{res}, t)$

Starting from the set of constraints  $\mathcal{R}$

- separate pre-preds constraints from post-preds constraints
- soundly derive definitions for the unknown predicates

Separate pre-preds constraints from post-preds constraints

$$(4). x \mapsto \text{tree}(p, l, r, t) * H_l(l, q, t) * H_p(p, q, t) * H_r(r, q, t) \wedge r = \text{NULL} \wedge \text{res} = x \\ \Rightarrow G(x, p, \text{res}, t)$$

Is split into:

$$(4a). H_r(r, q, t) \wedge r = \text{NULL} \Rightarrow \text{emp}$$

$$(4b). H_l(l, q, t) \Rightarrow \top$$

$$(4c). H_p(p, q, t) \Rightarrow \top$$

$$(4d). x \mapsto \text{tree}(p, l, r, t) \wedge r = \text{NULL} \wedge \text{res} = x \Rightarrow G(x, p, \text{res}, t)$$

This split enables separate refinements for pre and post predicates.

After the application of the refinement rules (see the paper):

$$H_l(l, q, t) \equiv H(l, x, lm)$$

$$H_r(r, q, t) \equiv \text{emp} \wedge r = \text{NULL} \vee H(r, x, t) \wedge r \neq \text{NULL}$$

$$H_p(p, q, t) \equiv \top$$

$$H_n(n, q, t) \equiv \top$$

$$H(x, q, t) \equiv x \mapsto \text{tree}(p, l, r, n) * H_l(l, q, t) * H_r(r, q, t) * H_n(n, q, t) * H_p(p, q, t)$$

$$G(x, p, \text{res}, t) \equiv x \mapsto \text{tree}(p, \_, r, t) \wedge \text{res} = x \wedge r = \text{NULL}$$

$$\vee x \mapsto \text{tree}(p, l, r, \_) * G(l, x, \text{res}, lm) * G(r, x, lm, t) \wedge r \neq \text{NULL}$$

# Normalization of predicate definitions



- User-Defined Predicate for binary tree

$$\text{pred } \text{bt} \langle \text{root} \rangle \equiv (\text{root} \mapsto \text{tree} \langle \_, \_, \text{NULL}, \_ \rangle) \\ \vee (\text{root} \mapsto \text{tree} \langle \_, \text{l}, \text{r}, \_ \rangle * \text{bt} \langle \text{l} \rangle * \text{bt} \langle \text{r} \rangle \wedge \text{r} \neq \text{NULL};$$

- User-Defined Predicate for tree with linked-leaves and parents

$$\text{pred } \text{tll} \langle \text{root}, \text{p}, \text{ll}, \text{lr} \rangle \equiv (\text{root} \mapsto \text{tree} \langle \text{p}, \_, \text{NULL} \rangle \wedge \text{root} = \text{ll}) \\ \vee (\text{root} \mapsto \text{tree} \langle \text{p}, \text{l}, \text{r}, \_ \rangle * \text{tll} \langle \text{l}, \text{root}, \text{ll}, \text{z} \rangle * \text{tll} \langle \text{r}, \text{root}, \text{z}, \text{lr} \rangle \\ \wedge \text{r} \neq \text{NULL};$$

- Inferred Specification

$$\text{requires } \text{bt} \langle \text{x} \rangle \quad \text{ensures } \text{tll} \langle \text{x}, \text{p}, \text{res}, \text{t} \rangle;$$

- 1 Overview
- 2 `get_data` Example
- 3 `s112d11` Example
- 4 `t11` Example
- 5 Implementation and Experiments

# Shape Inference: Implementation and Experiments

Example	Syn.	Veri.	Example	Syn.	Veri.
SLL (reverse)	0.21	0.2	SLL2DLL	0.19	0.18
SLL (insert)	0.2	0.2	DLL (check)	0.21	0.19
SLL (setTail)	0.16	0.16	DLL (append)	0.2	0.2
SLL (get-last)	0.7	0.21	CDLL (c)	0.22	0.21
SLL-sorted (c)	0.26	0.22	CDLL of 5CSLLs (c)	0.39	1.3
SLL (bubblesort)	0.28	0.26	CDLL of CSLLs <sub>2</sub> (c)	0.33	0.29
SLL (insertsort)	0.3	0.27	btree (search)	0.23	0.23
SLL (zip)	0.27	0.24	btree-parent (t)	0.23	0.24
SLL + tail (c)	0.19	0.18	rose-tree (c)	0.28	0.23
skip-list <sub>3</sub> (c)	0.36	0.3	swl (t)	0.23	22
SLL of 0/1 SLLs	0.25	0.23	mcf (c)	0.26	0.26
CSLL (t)	0.22	0.24	tll (t)	0.23	0.21
CSLL of CSLLs (c)	0.24	0.22	tll (set-parent)	0.24	0.24

**c** for *check* and **t** for *traverse*

- **S2**: <http://loris-7.ddns.comp.nus.edu.sg/~project/s2/beta/>
- synthesis < **1s** for all examples

# Shape Inference: Implementation and Experiments

S2: <http://loris-7.ddns.comp.nus.edu.sg/~project/s2/beta/>

	LOC	#Proc	#Loop	#√	Syn. (second)
gsl.c	698	33	18	47	11.73
glist.c	784	35	19	49	7.43
gtree.c	1204	36	14	44	3.69
gnode.c	1128	37	27	52	16.34

- GLIB open source
- gtree: balanced binary tree. gnode: N-ary tree.
- shape analyse successfully for **89%** of procedures/loops (192/216)
- limitation: overlaid data structures, array pointers, combined shape + pure (e.g. get\_data\_nth)



# Normalization Experiment

Example	w/o norm.		w/ norm.	
	size	Syn.	size	Syn.
SLL (get-last)	20	0.24	17	0.24
SLL-sorted (c)	8	0.26	2	0.27
SLL (zip)	12	0.31	2	0.31
skip-list <sub>3</sub> (c)	17	0.45	1	0.46
CSLL (t)	8	0.23	5	0.23
CSLL of CSLLs (c)	18	0.24	4	0.23
SLL2DLL	18	0.19	2	0.2
DLL (append)	11	0.2	8	0.2
CDLL (c)	23	0.22	8	0.26
CDLL of 5CSLLs	28	0.39	4	0.66
CDLL of CSLLs <sub>2</sub>	29	0.33	4	0.44
tree-parent (t)	11	0.23	2	0.29
rose-tree (c)	14	0.28	14	0.3
mcf (c)	19	0.26	17	0.28
tll (t)	21	0.23	2	0.25

reduce by **68%**  
(169/533) the  
number of  
conjuncts with a  
time overhead of  
**26%**  
(8.37s/10.62s)

## Shape Inference

- 1 scalability: potential
- 2 expressive data structures: ✓
- 3 soundness: ✓

Thank you!